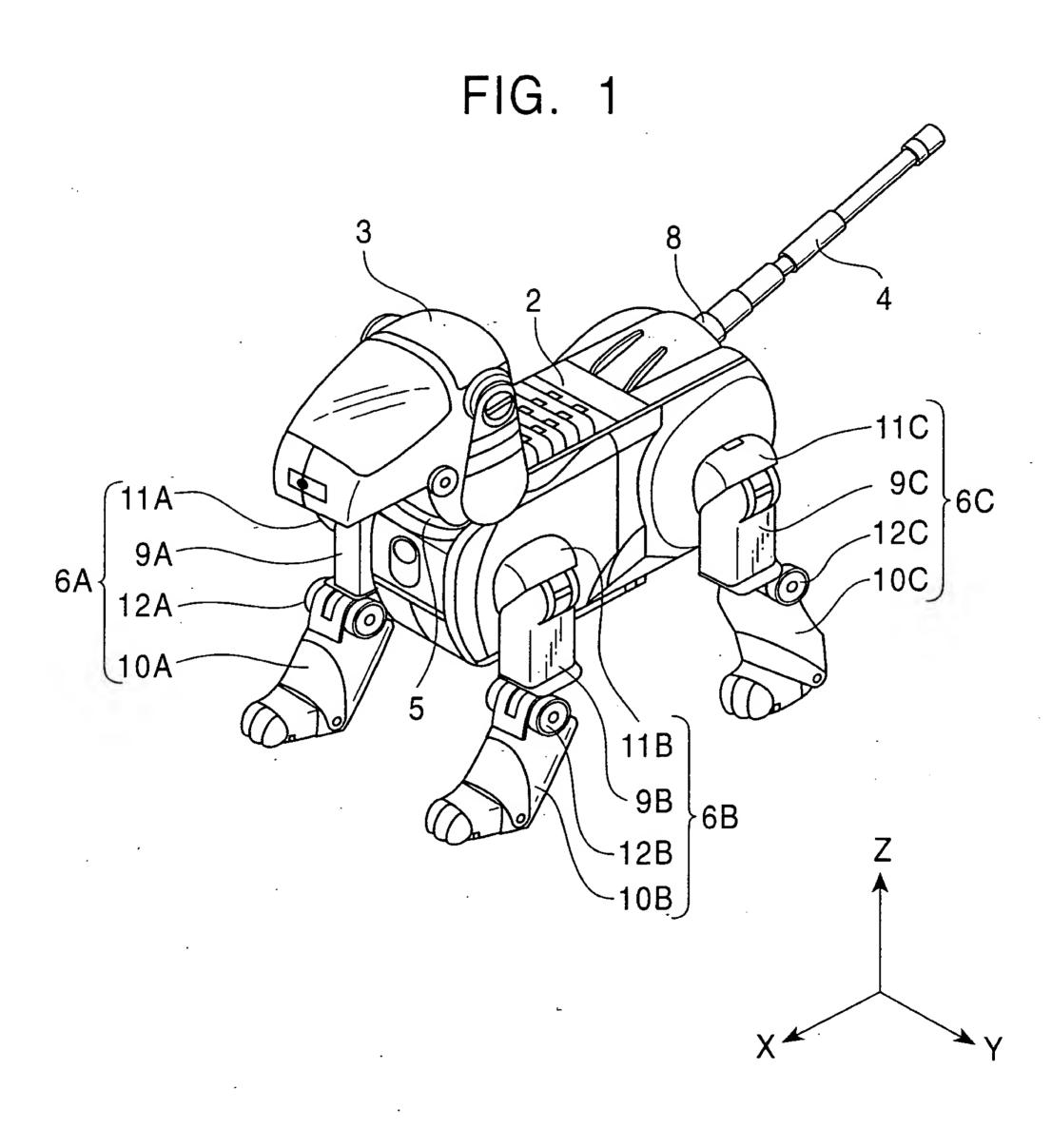


1/24





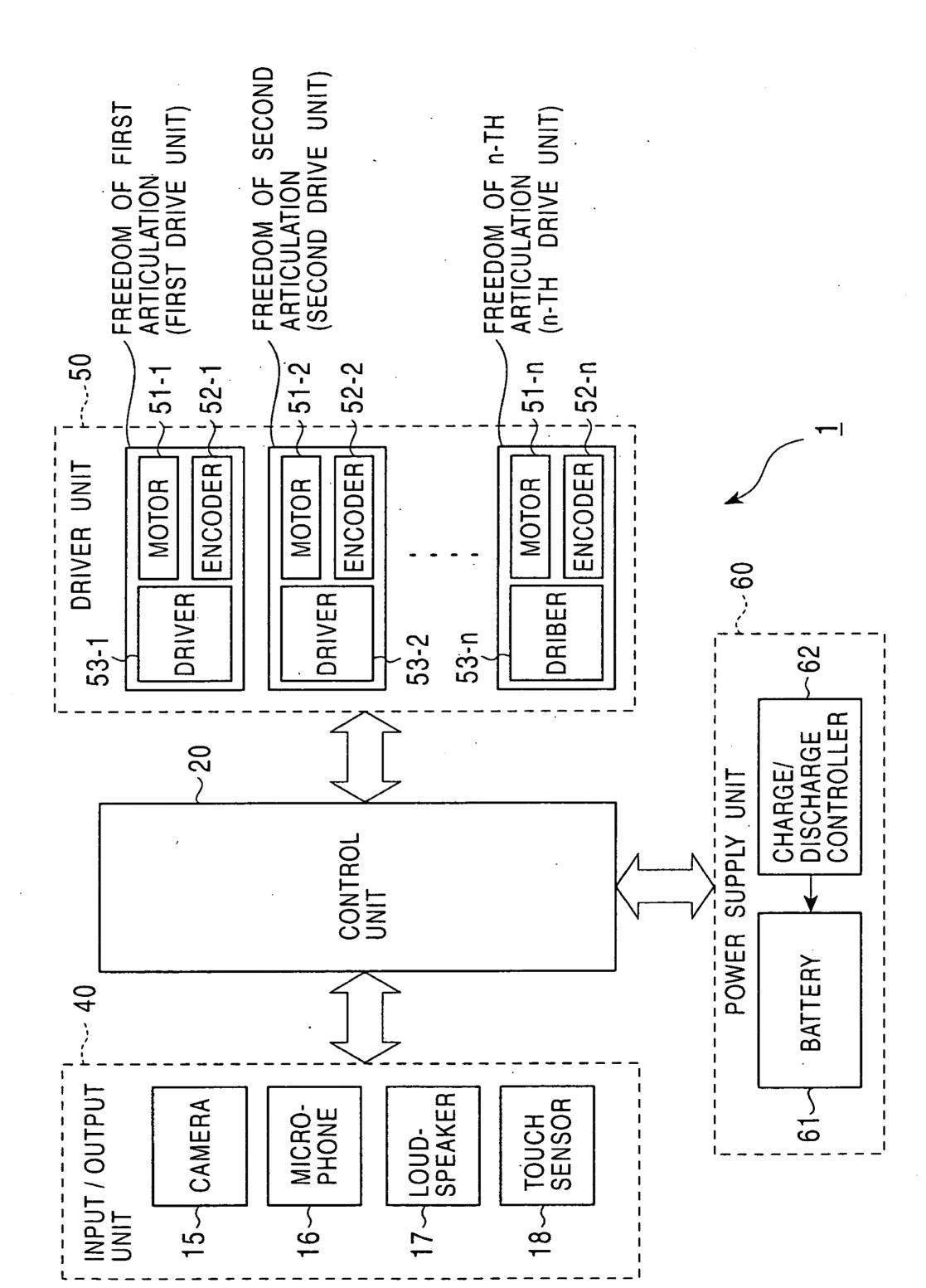
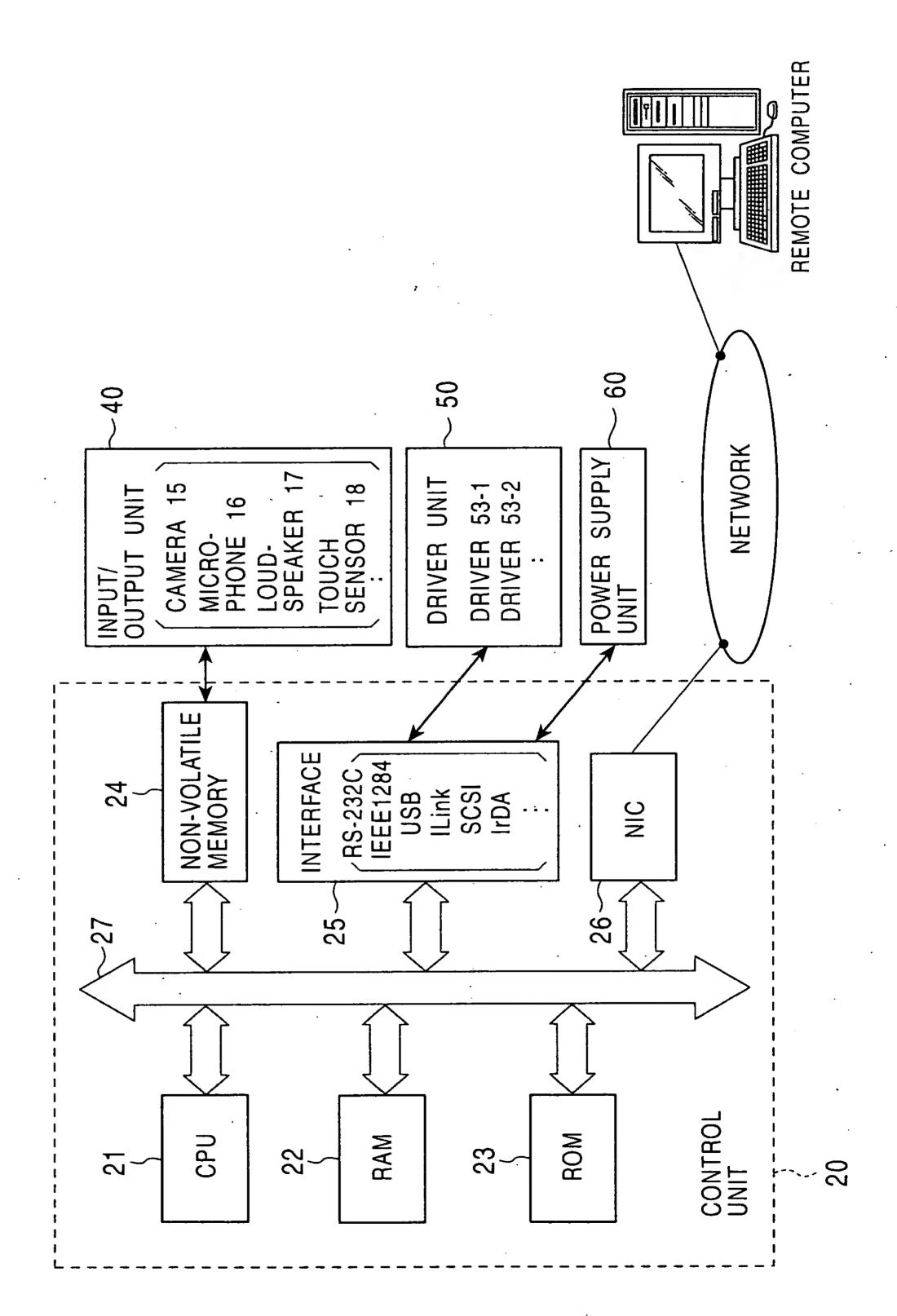


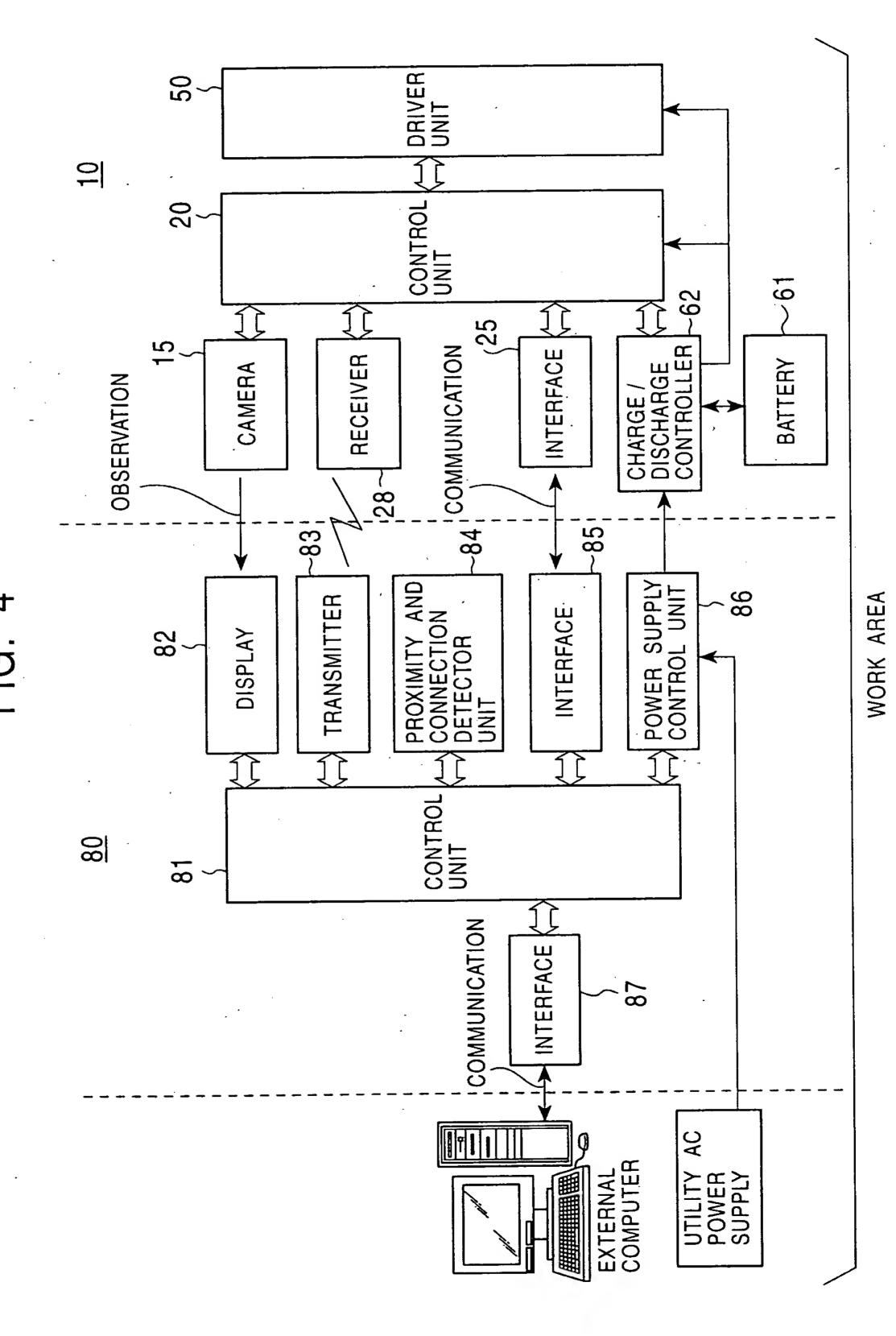
FIG. 3

O.G. FIL

**EY** 

DEAFTEMAN





5 / 24

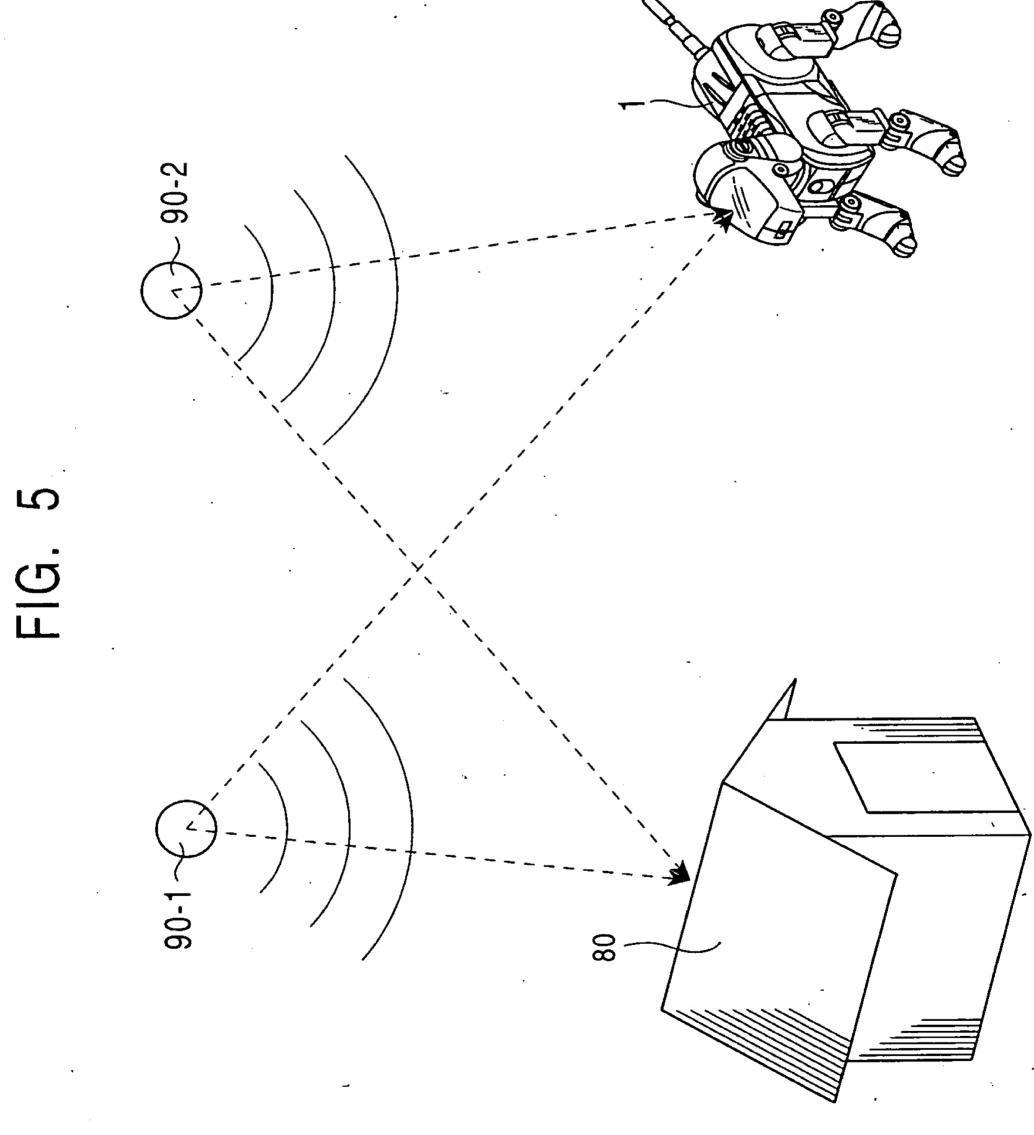
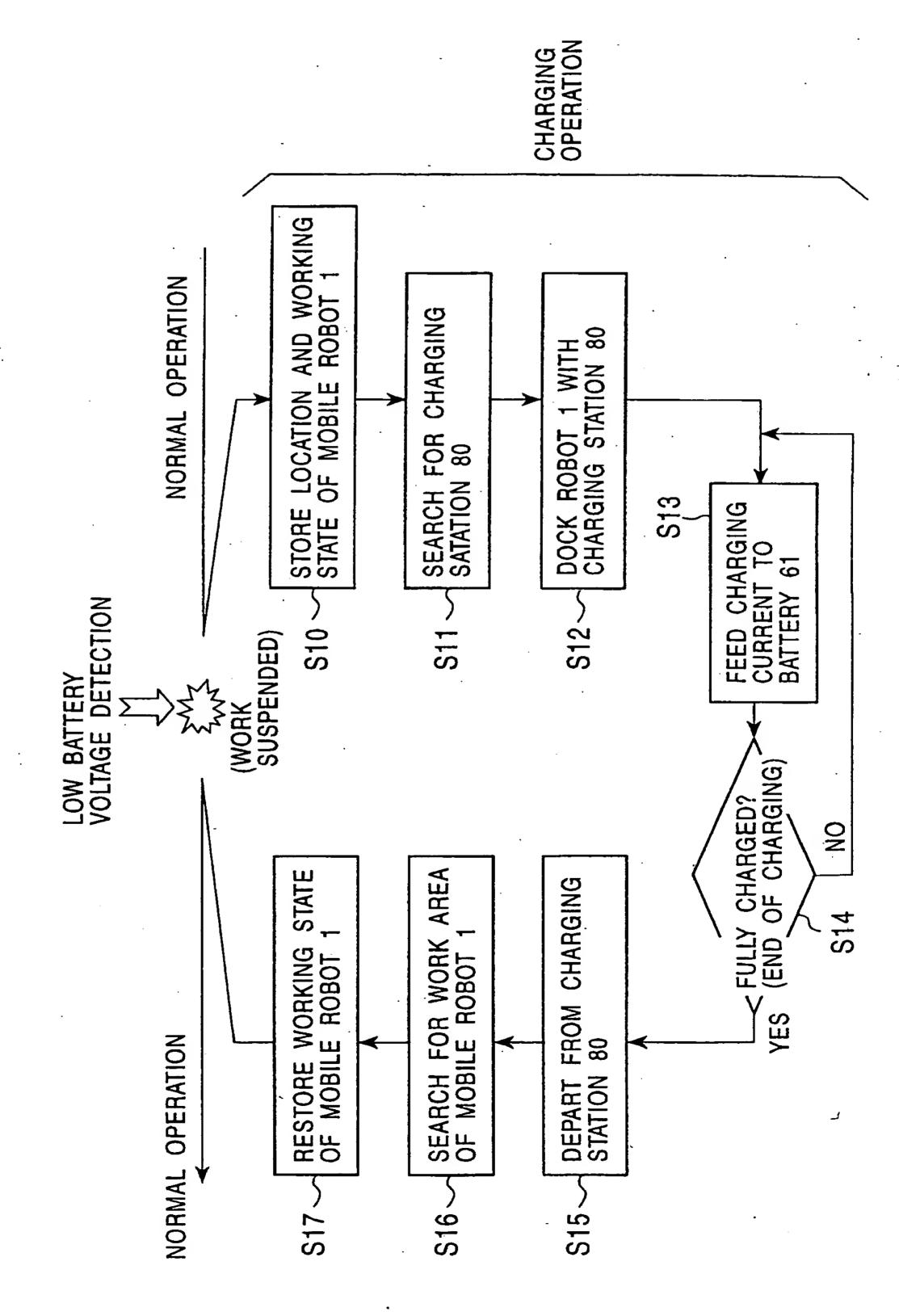
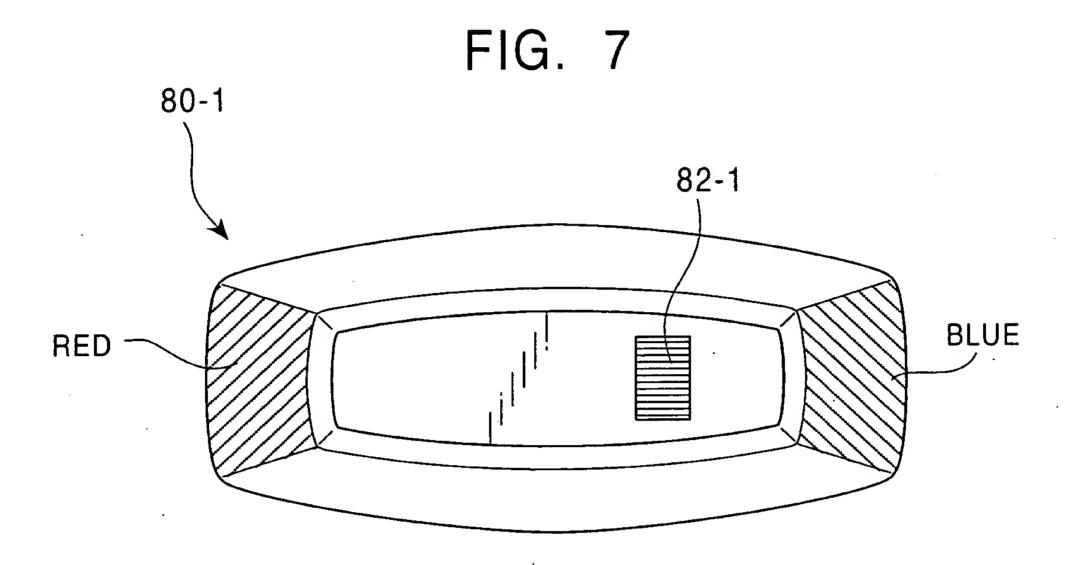
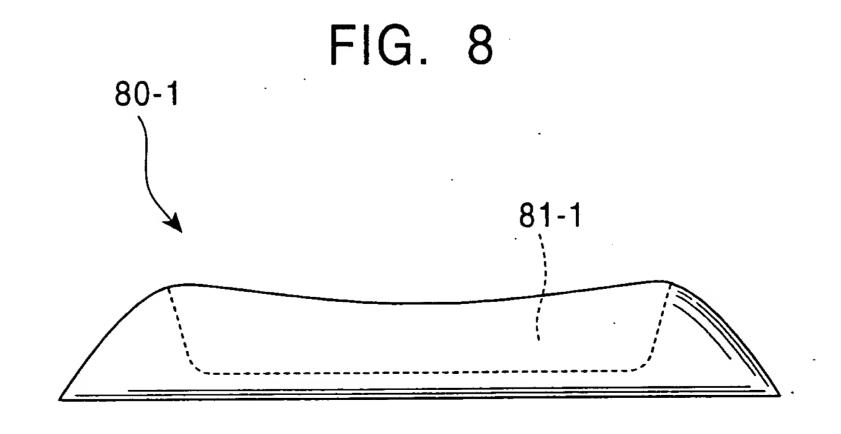
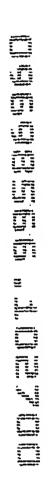


FIG. 6









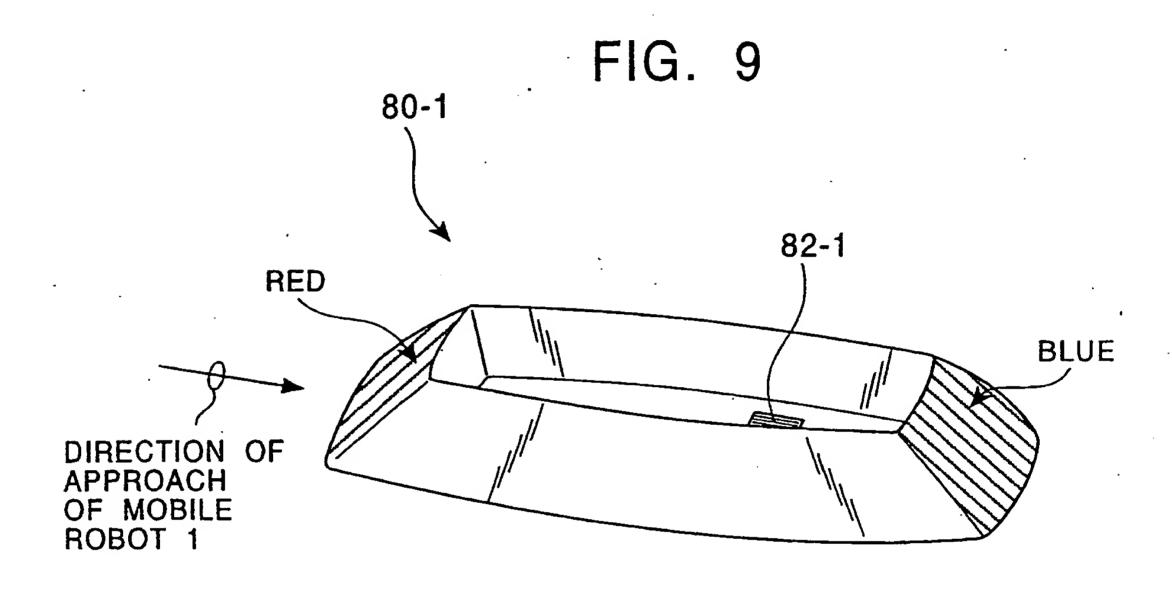


FIG. 10

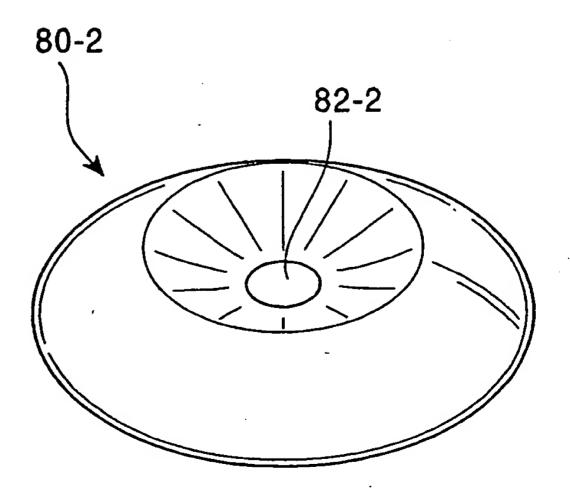


FIG. 11

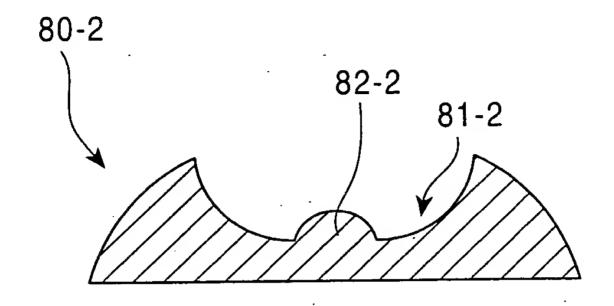
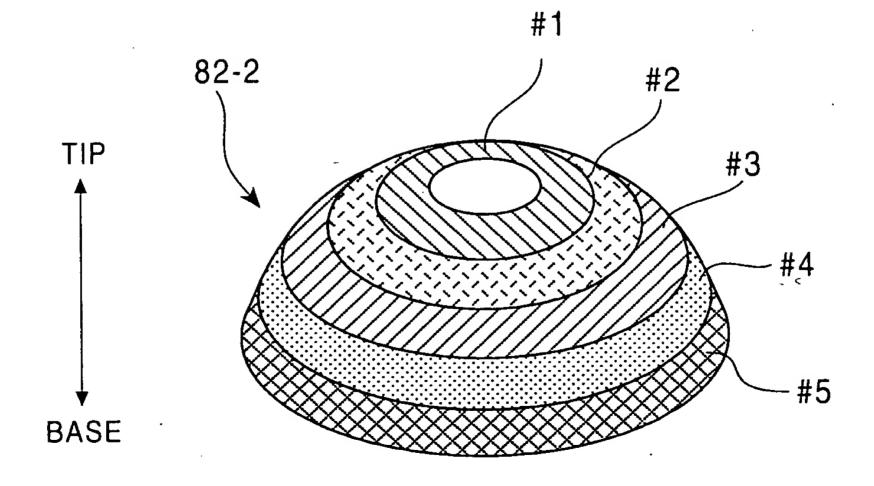
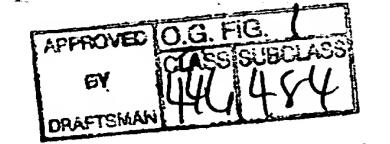


FIG. 12





## FIG. 13

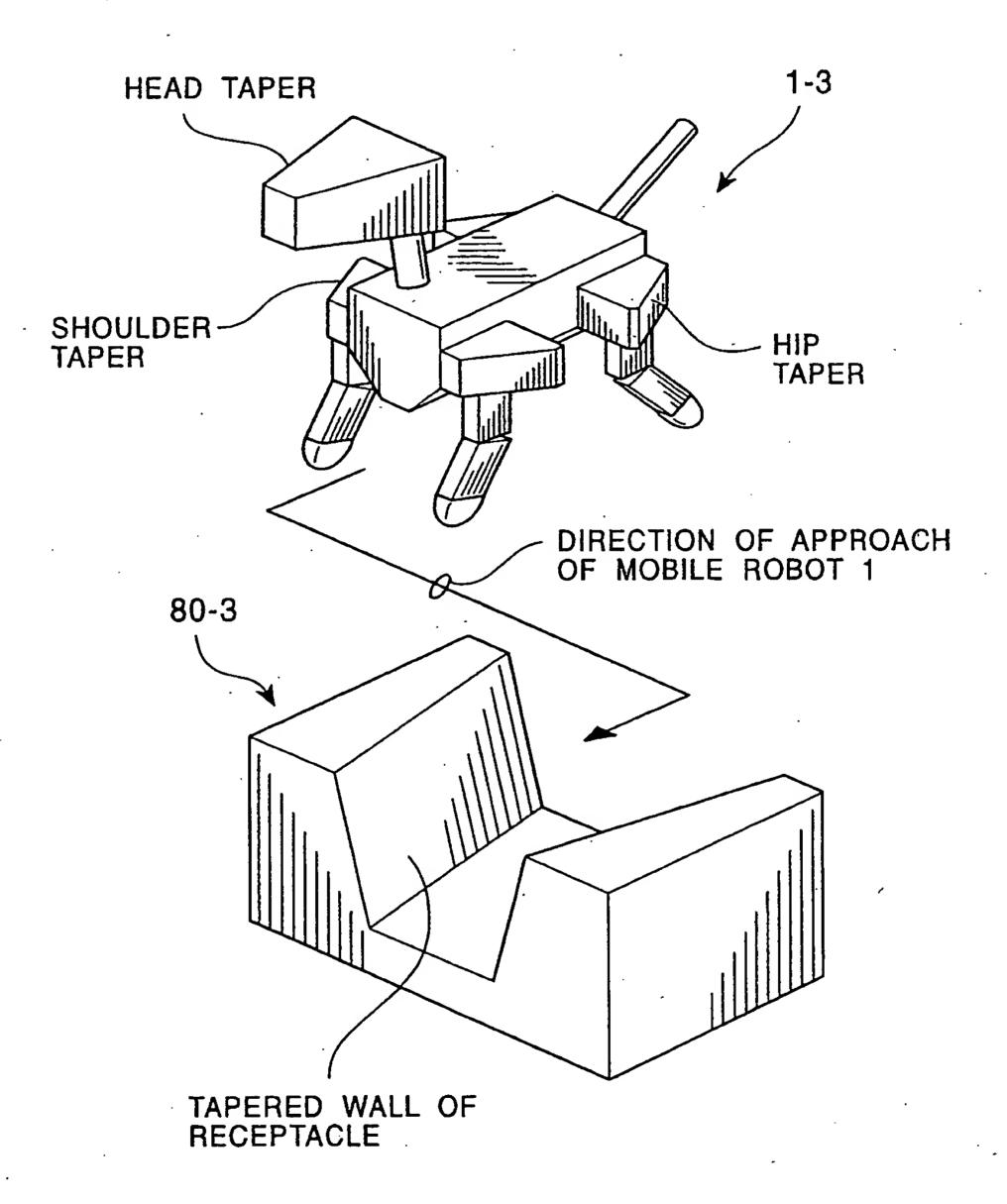




FIG. 14

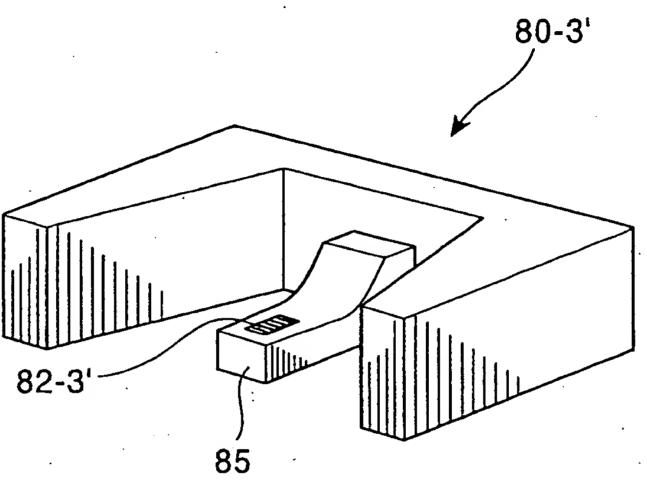
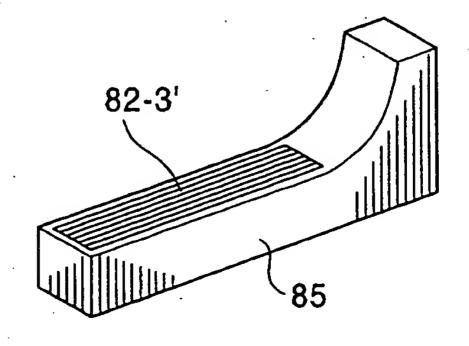


FIG. 15



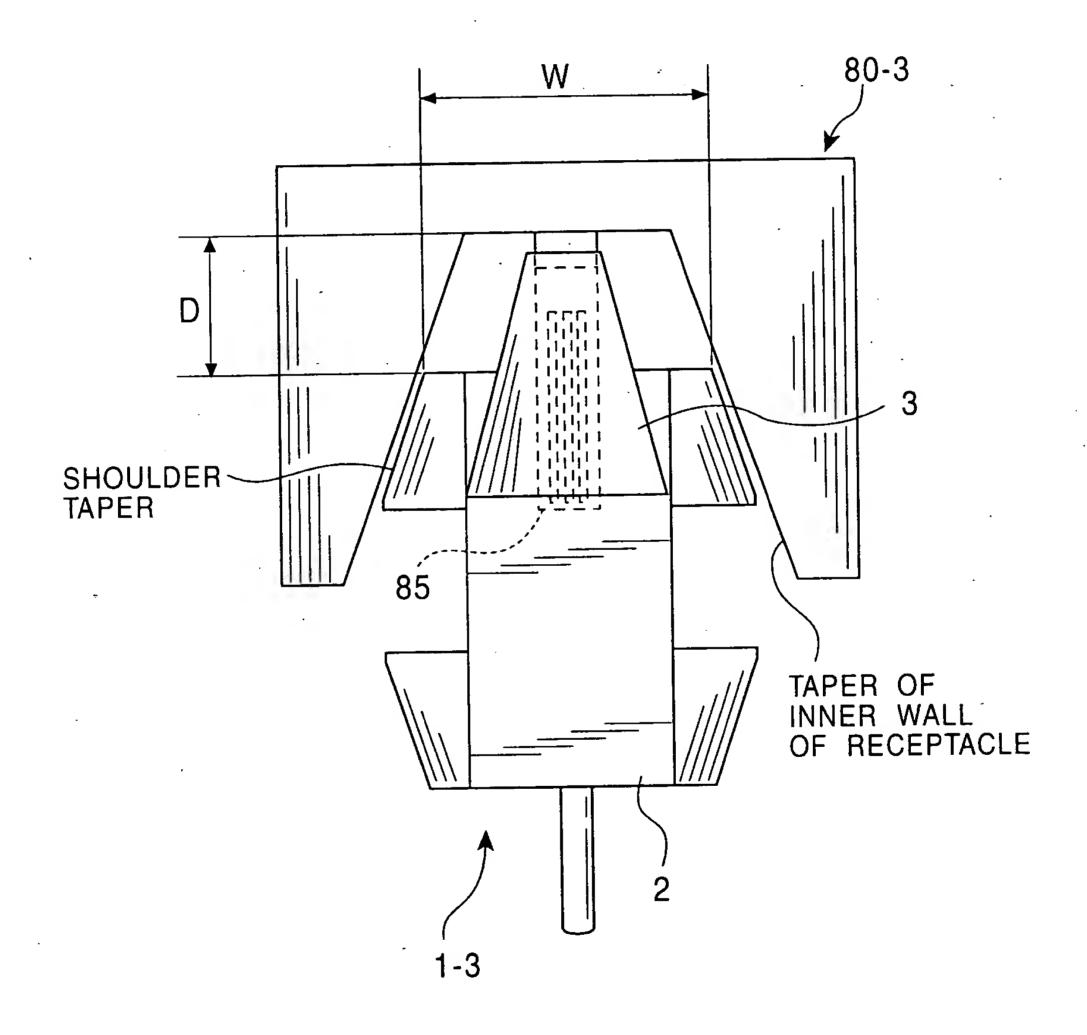
DIRECTION OF APPROACH OF MOBILE ROBOT 1

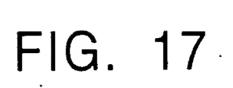


APPROVED O.G. FIG.

DPAFTSMAK

FIG. 16





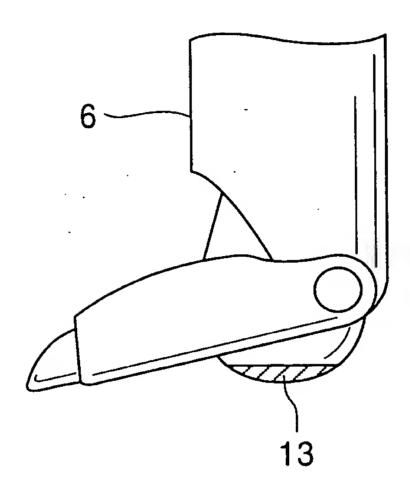


FIG. 18

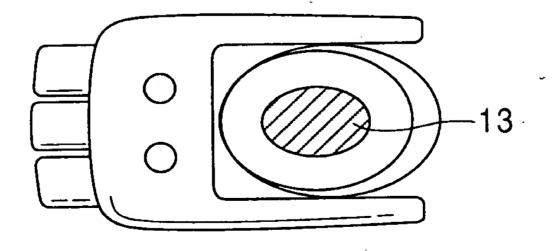


FIG. 19

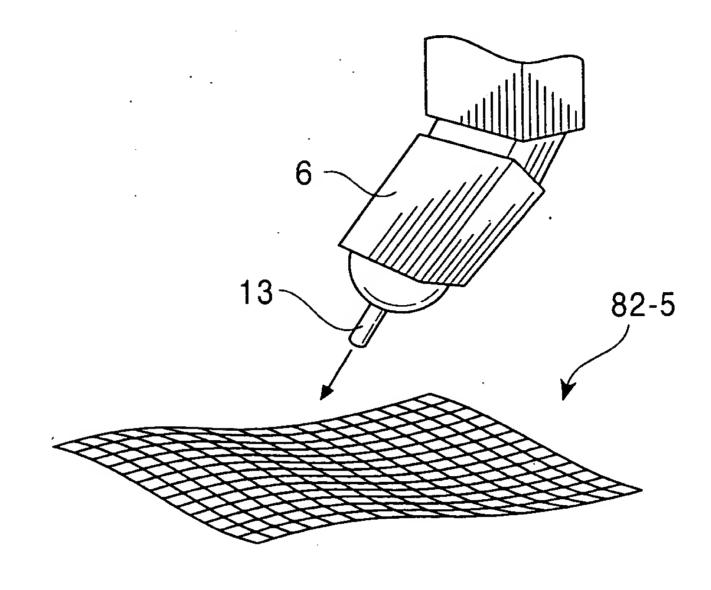
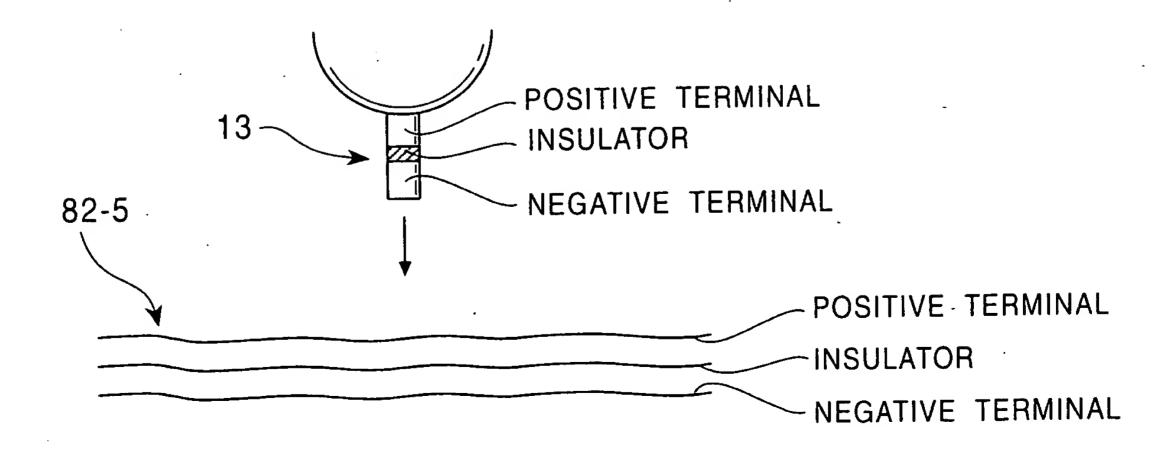


FIG. 20





APPROVED O.G. FIG



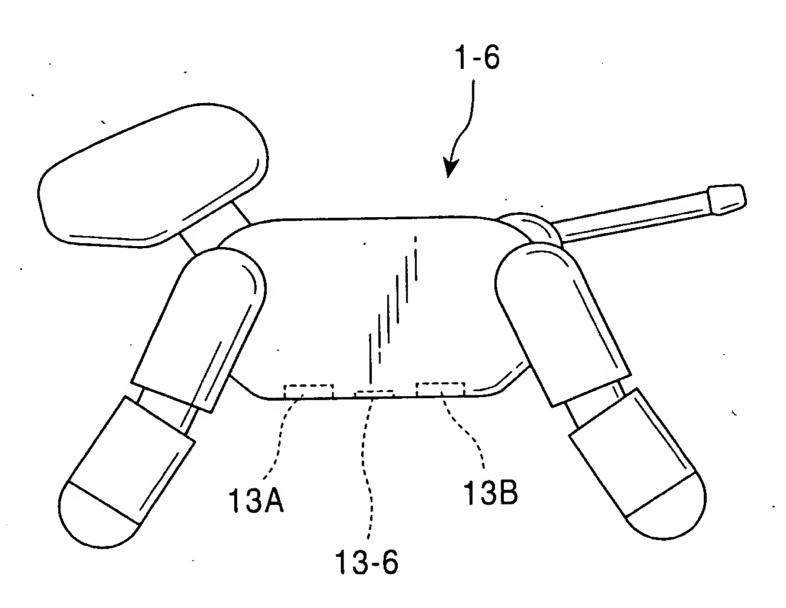
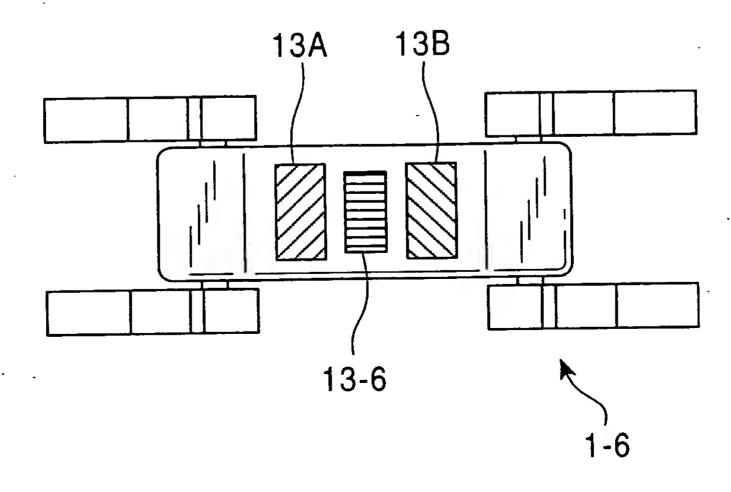


FIG. 22





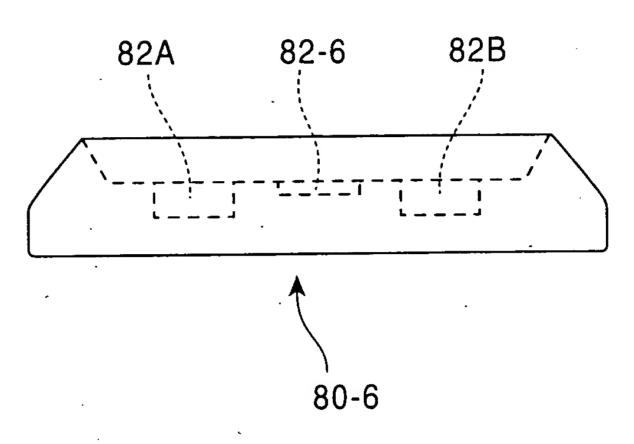


FIG. 24

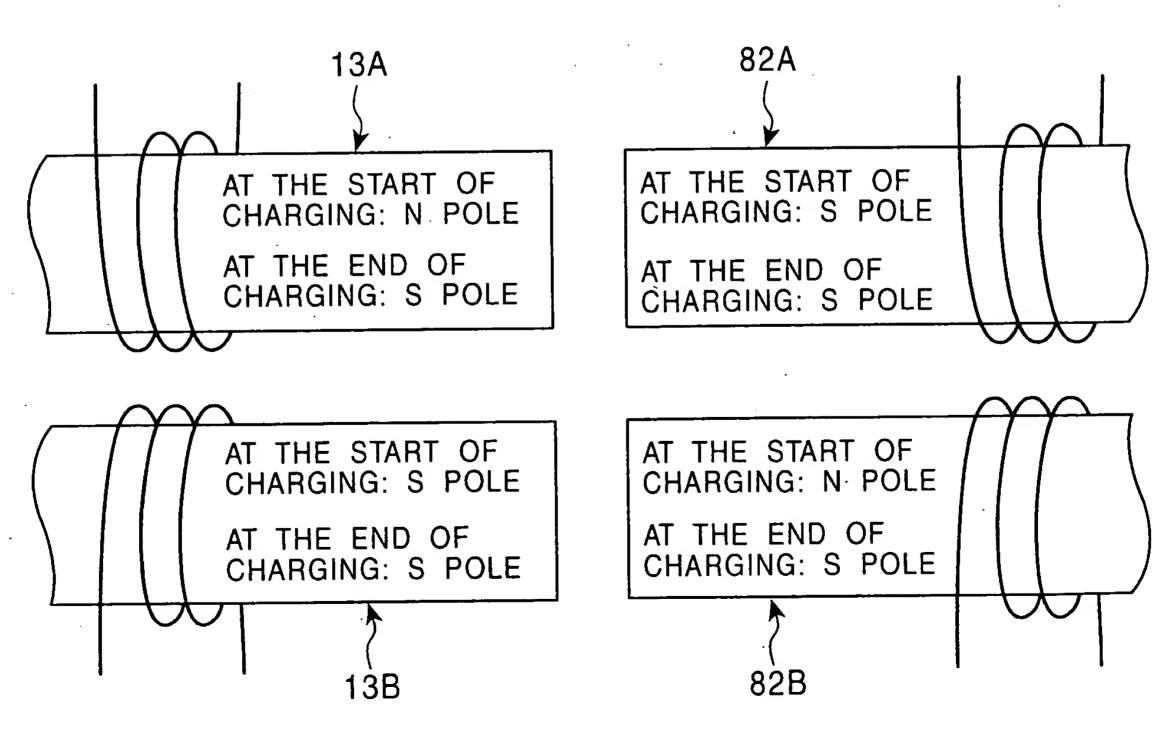


FIG. 25

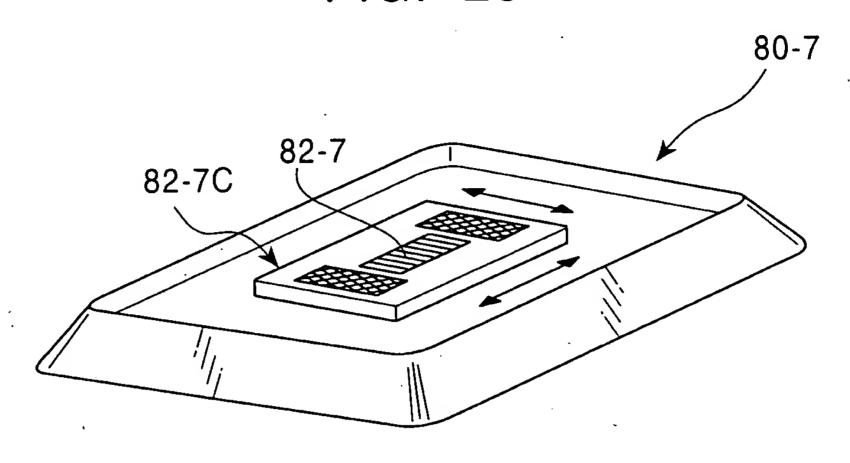
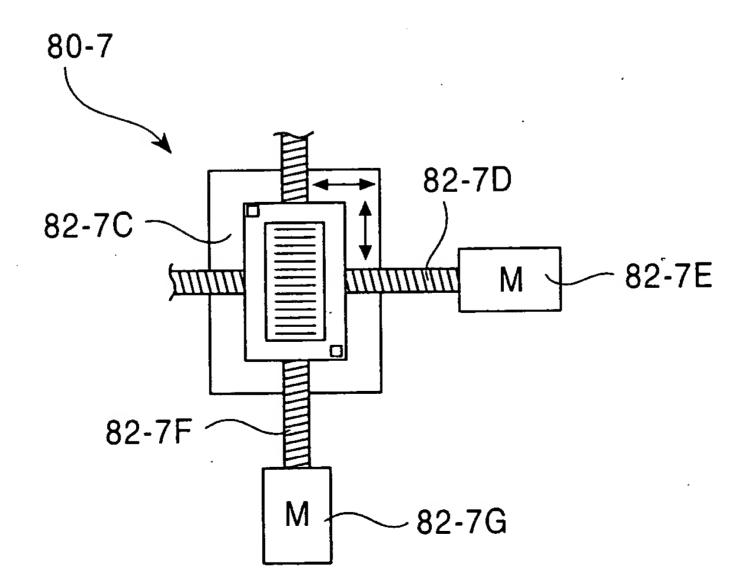
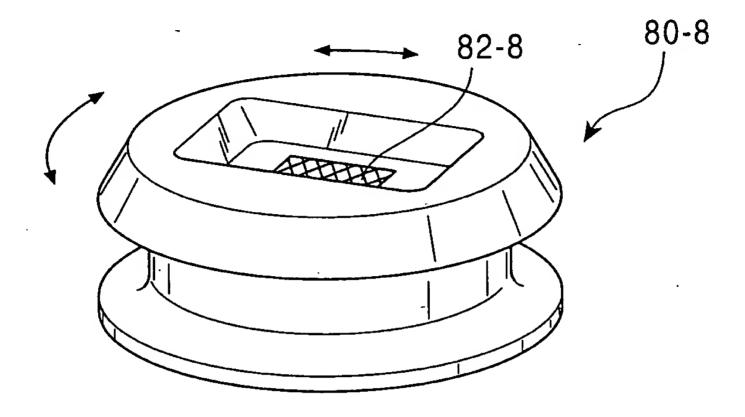


FIG. 26







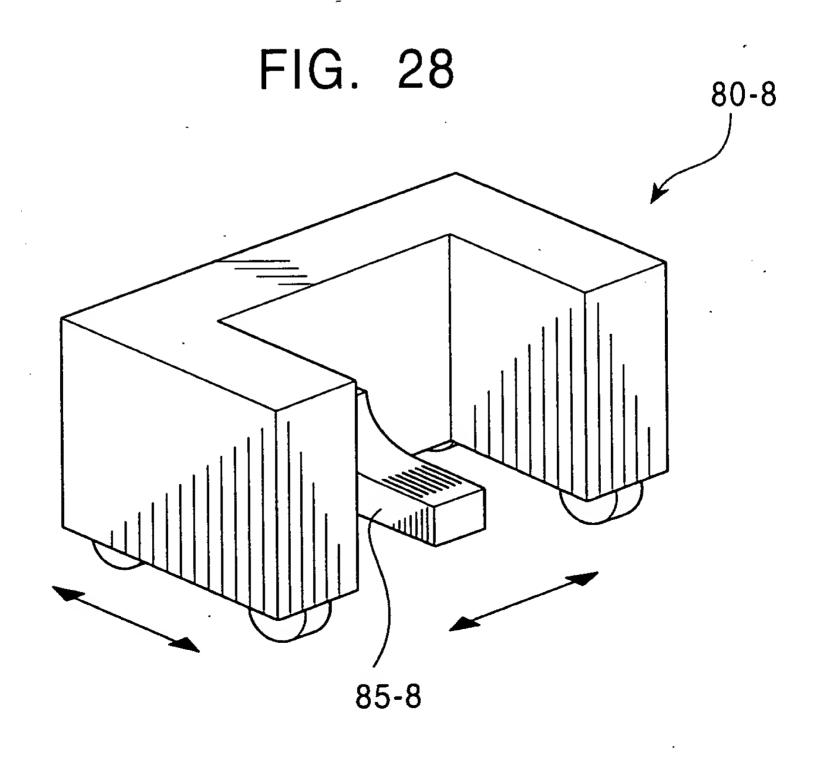






FIG. 29

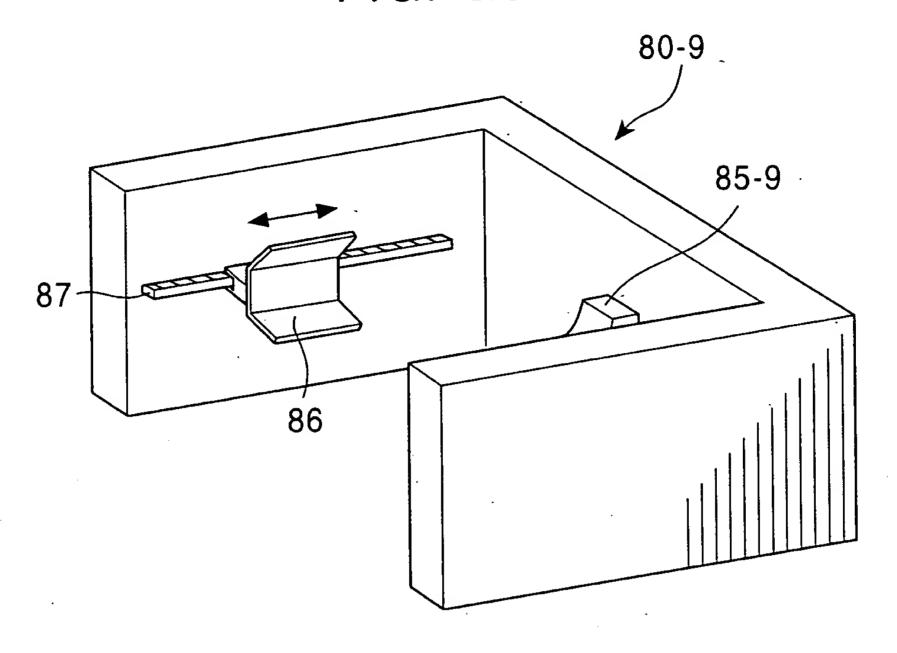


FIG. 30

80-10

1-9

6C,6D

2

6A,6B



 $20 \angle 24$ 

FIG. 31

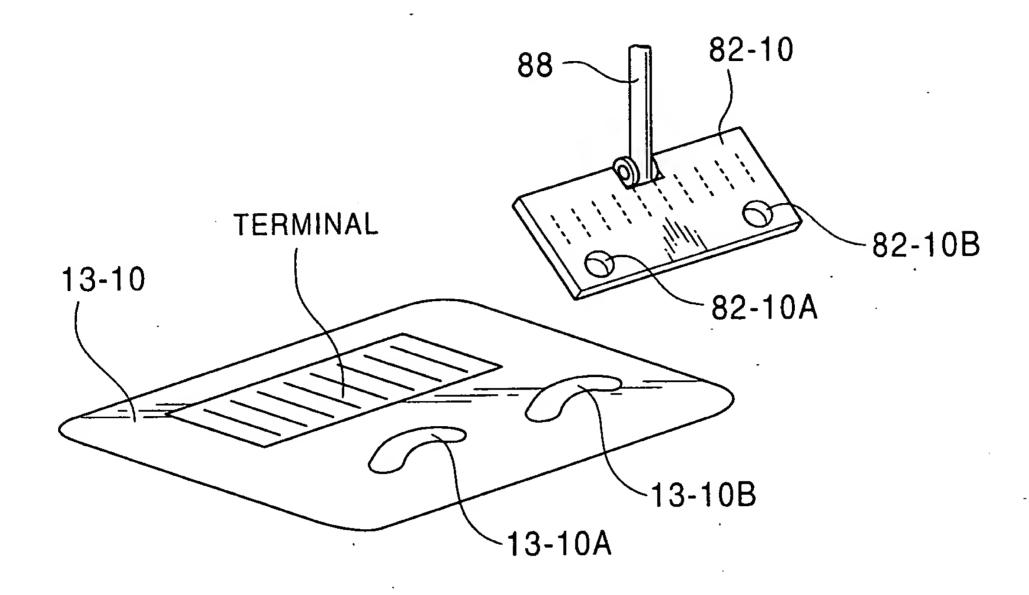
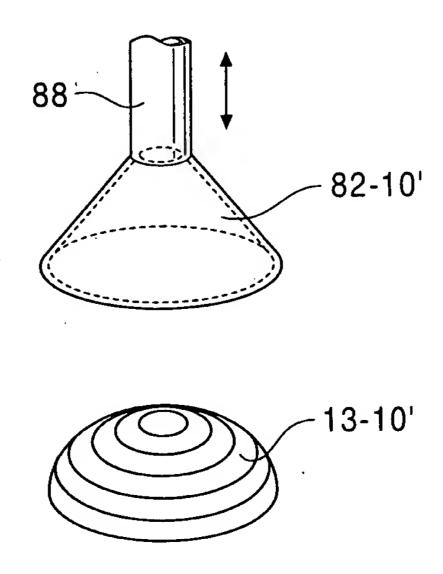
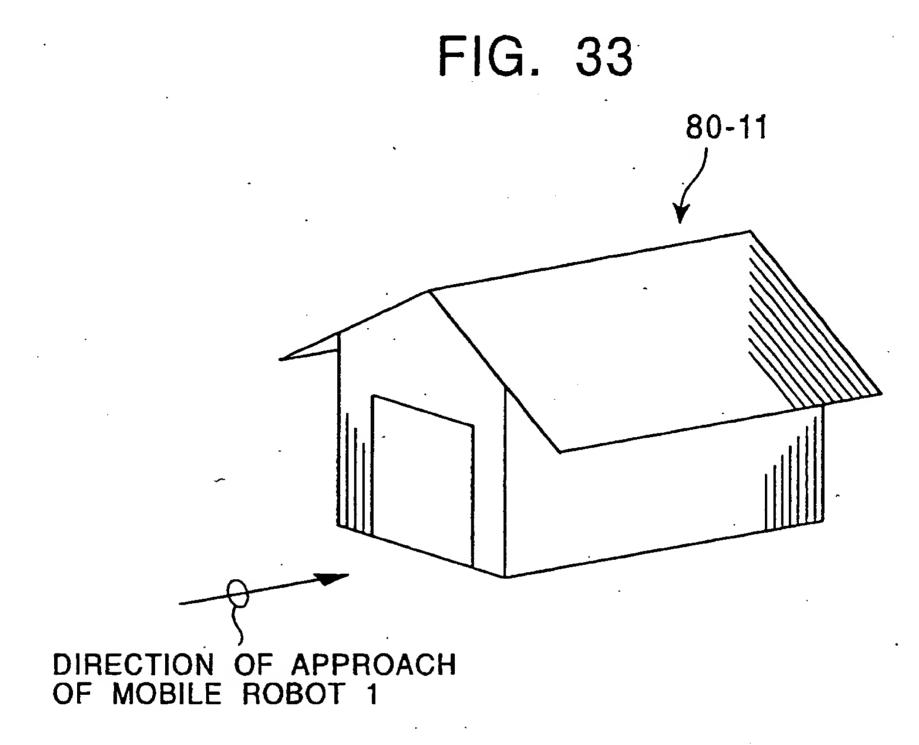
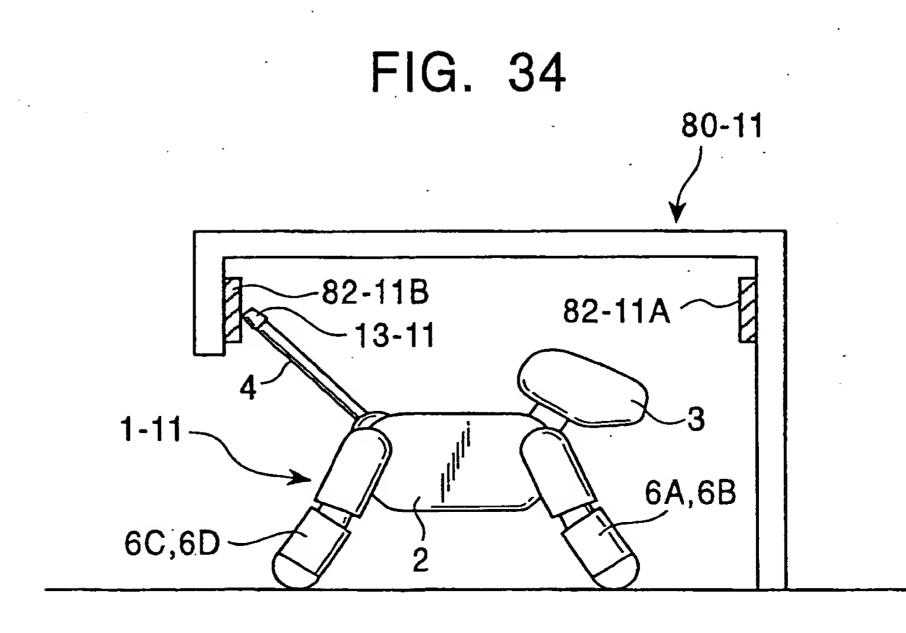


FIG. 32







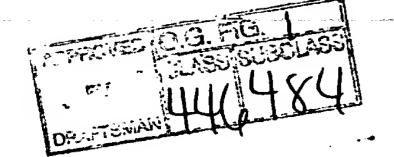


FIG. 35

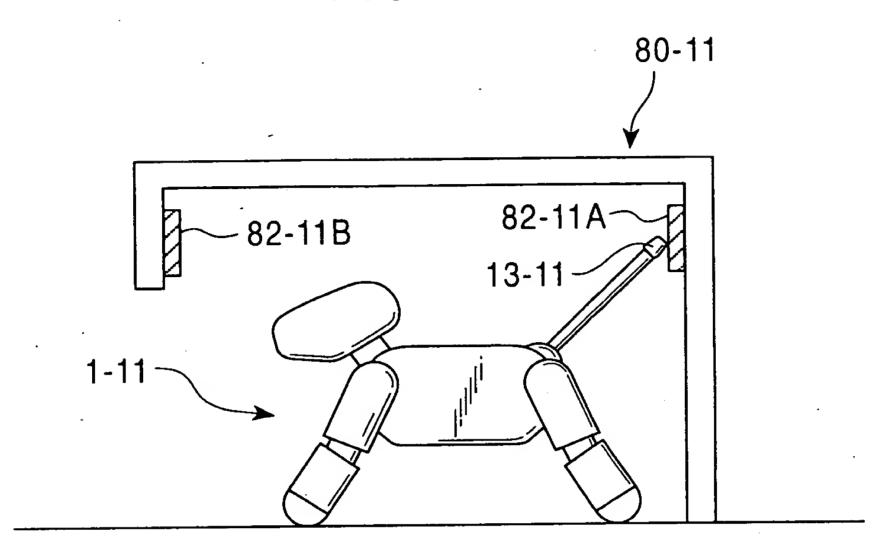
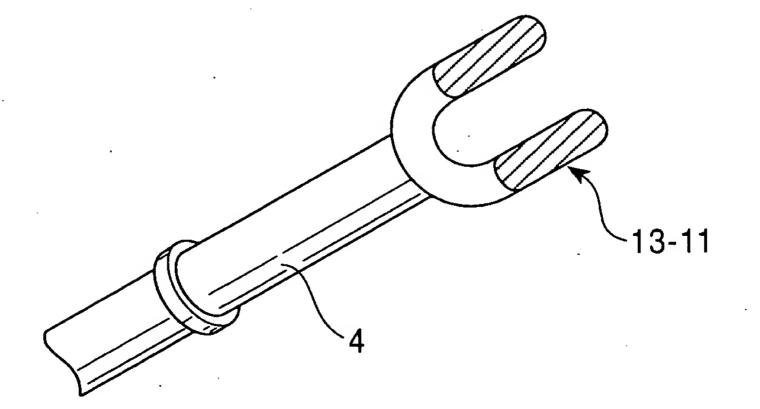


FIG. 36



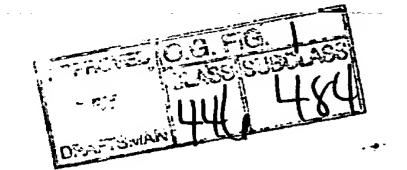


FIG. 37

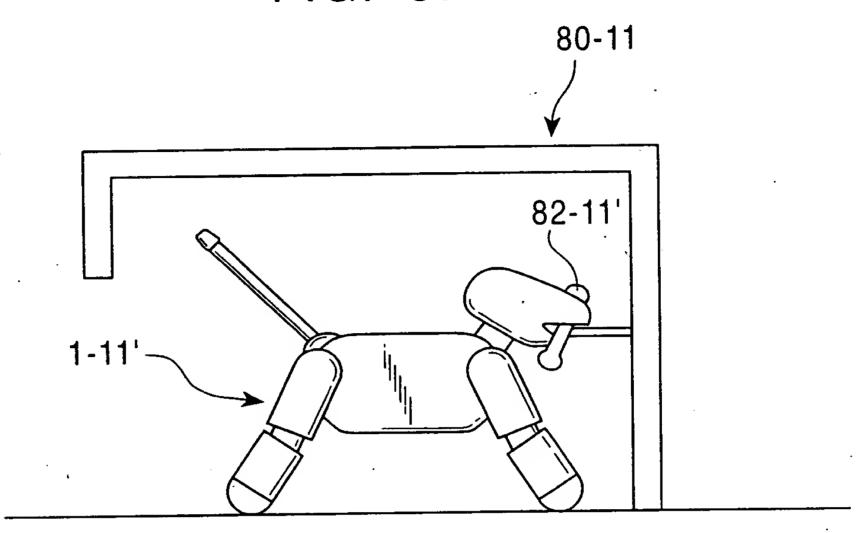


FIG. 38

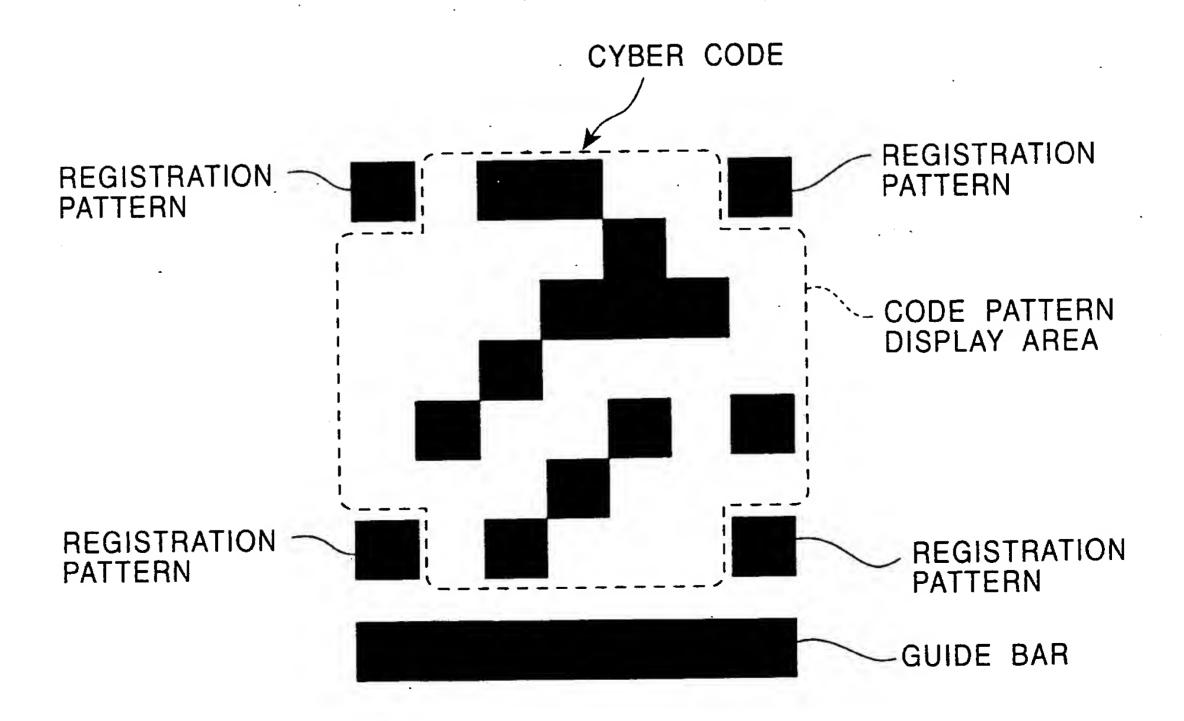


FIG. 39

